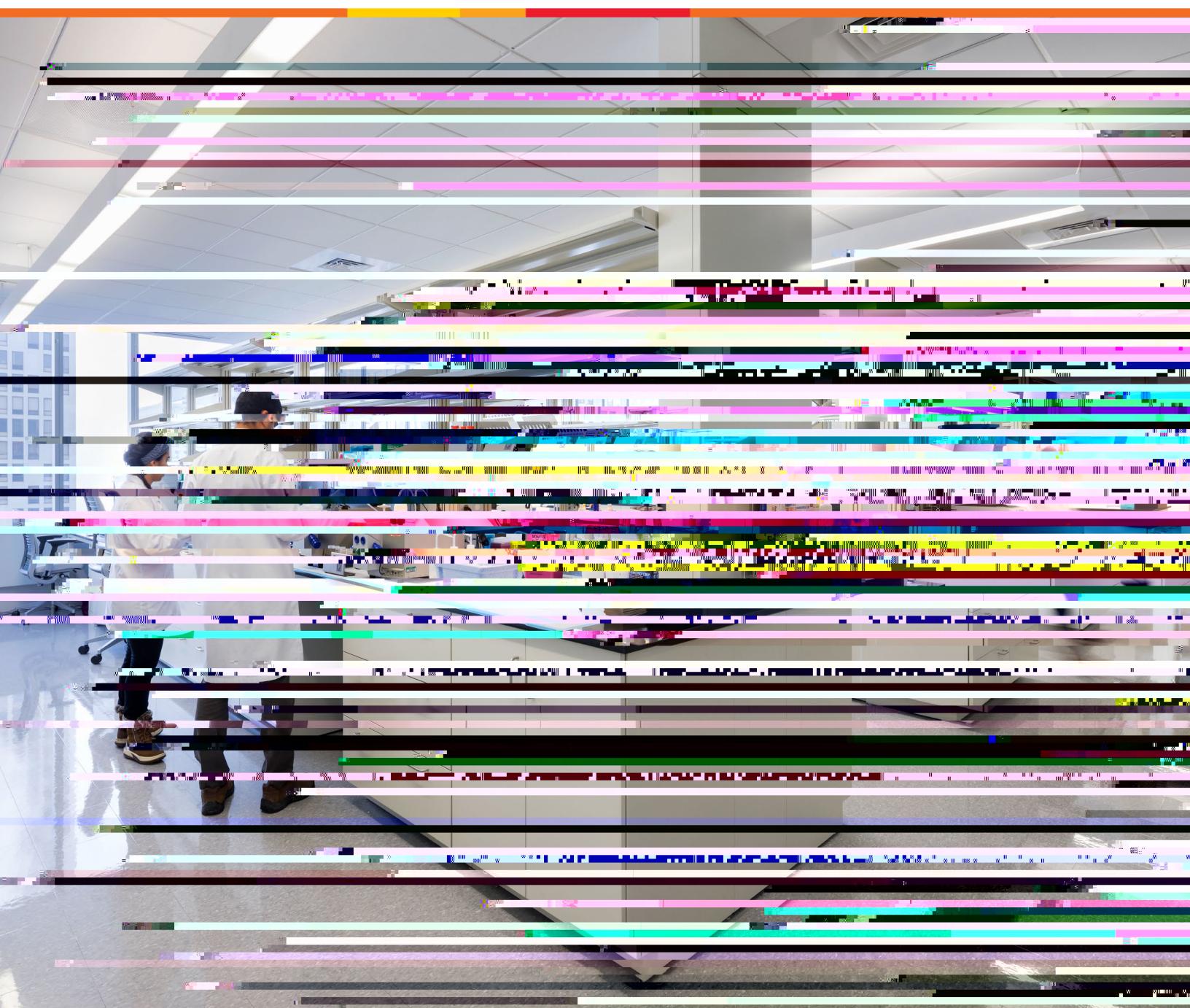


# Research101

A QuickStarGuide for Research at Shirley Ryan AbilityLab



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vision is “*to be the global source of science-driven breakthroughs in Human Ability.*” This vision

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# Let's Get Started by Bragging a Bit

As you may have noticed, I am a Software Engineer at Microsoft.

- Shirley Ryan AbilityLab





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## ROUNDTABLES

K v %œ œ Roun~~Table~~ting together Shirley Ryan AbilityLab clinicians and researchers  
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## NURSING FELLOWSHIPS/GRANTS

Registered Nurses and Advanced Practice Registered Nurses may apply for funding to conduct research and/or teach. Applications are due by the end of the year.



# Time to Learn the Basics ...

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## Community research

Community research is a process of inquiry that involves the collection and analysis of data from a specific community or group of people. The goal of community research is to gain a better understanding of the needs, concerns, and experiences of the community members, and to use this information to inform decision-making and action. Community research can be conducted through various methods, such as surveys, interviews, focus groups, and case studies. It is often used to address social issues and improve the quality of life for community members.

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[kearnest@sralab.org](mailto:kearnest@sralab.org)

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## **BIOSKETCH EXAMPLE**

The following two biosketches have been used in recent grant submissions.

- x The first was used by Levi Hargrove to obtain a large NIH grant to evaluate osseointegration with implanted electrodes to improve ability for individuals with upper-limb amputation.
- x The second was used by Kristi Turner to apply for a Department of Defense grant to evaluate outcome when using a prosthetic limb.



3. L. Hargrove, *ÉS ÓA* \* |^@ed Å ÁÓÉP ^ å\* à • ÉAOZÓ[ { } æå[ ] Á• ÁU^ | -&^ Áå ÁÓdå^ ~• & |æÁ^ [ ^|^&då^ Ùå } æÓlæ• åBæ{ } +ÓÓÓÓÁ\æ• åBæ{ } • Á } Áó{ ^åBæ{ } \* à^~|ä^ \* ÉI K I Í -853, 2007. PMID:17518281

4. L. Smith, T. Kuiken, and L. Hargrove, *ÉO då^ ~• & |æÁOT ÓÁ[ , Áf |ÁU^@ Time, Simultaneous and Ú[ ] [ ] å^ [ ^|^&då^ ] d[ |ÉJournal of Neural Engineering*, 11(6), 066013, 2014. PMC4268782

#### **B. Positions, Scientific Appointments, and Honors**

## **Positions, Employment, and Scientific Appointments**

*Shirley Ryan AbilityLab*

2017. present

2016. 2017

2008-present

Director and Scientific Chair, Center for Bionic Medicine

## Associate Director, Center for Bionic Medicine

Research Scientist, Shirley Ryan AbilityLab (previously RIC)

*Northwestern University*

2016, present

2016. present

2015-2016

2014 2016

Associate Professor, Biomedical Engineering

Associate Professor, Physical Medicine & Rehabilitation

Assistant Professor, Biomedical Engineering

Assistant Professor, Physical Medicine & Rehabilitation

**2014-2015** Assistant Professor, Physical Medicine & Rehabilitation  
**2008-2014** Research Assistant Professor, Physical Medicine & Rehabilitation

#### **Other Experience and Professional Memberships**

Associate Editor, *IEEE Transactions on Medical Robotics and Bionics*

Associate Editor, IEEE Transactions on  
Founding Partner, Coapt LLC

CDMRP Program Grant Peer Reviewer - PROP 88 ov GRIFF JET@185.42.315

2012. presse

2012-2013  
2011-present

2011. present  
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2008. present

fact, the focal nature of the intramuscular EMG signal recording could result in reduced performance if the motor unit pool was only sparsely sampled. I completed a set of experiments to show that the system performed equivalently to a system which used surface EMG signals. More recently, we have shown that we can alter our control approaches to take advantage of the more focal recordings and to produce a simultaneous multifunction control system, which is an advance in the field.

- a. L. Hargrove, J. Birdwell, and R. X. Uqdoh, "Simultaneous Control of Multiple Functions Using Intramuscular EMG Recordings," *IEEE Transactions on Biomedical Engineering*, 54:847-853, 2007. PMID:17518281
- b. J. Birdwell, L. Hargrove, and R. X. Uqdoh, "Muscles and Compartments of the Extrinsic Finger Muscles," *Journal of Hand Surgery - American Volume*, 38(6):1385-1392, 2013. PMC3763151

d.



1R44HD110334-01A1 Subaward (Co-I: Turner)

User-centered Design of Digital Health Technology for Clinicians Treating Upper-Limb Myoelectric Prostheses Wearers

5/17/2023 ±4/30/2025 The goal of this study is to improve the design and implementation of digital health technology in real-world clinical settings for upper-limb prosthesis users and their clinical care providers. The information gathered will be used to design a web-based digital health portal that will contain data and analyses related to upper-limb prosthesis use and performance in their home and community. The web portal will be to assist prosthetists/occupational therapists providing clinical care and provide extended telehealth support to upper-limb prosthesis users.

B. Positions , Scientific App ointments, and Honors

Positions and Employment

2012 - Research Occupational Therapist, Shirley Ryan AbilityLab, Chicago, IL

2012 -

C. Contributions to Science

1. Though outcome measures are needed to evaluate the new control and devices developed in the CBM, I have also been involved in efforts to identify the best outcomes and to refine existing outcomes. In 2019, I was part of an international team to refine the training and evaluation materials for one of the widely used functional measures, the ACMC. We continue to refine the measure to be appropriate to properly evaluate new prosthetic components, such as multifunction hands. I continue to work to explore new ways to train prosthetic users, with both body- powered and externally-powered systems, and assess and improve prosthetic function and control.
  - a. Hermansson, L. N., and Turner, K. (2017). Occupational Therapy for Prosthetic Rehabilitation in Adults with Acquired Upper-Limb Loss: Body-Powered and Myoelectric Control Systems. *Journal of Prosthetics and Orthotics* (12).
  - b. L. Hargrove, L., Miller, L., Turner, K.

- b. Sensinger, J., Lipsey, J., Thomas, A., and Turner, K . (2015). ³' H V L J Q D Q G H Y D O X D W L F  
voluntary opening and voluntary F O R V L Q J S U R V W K H W L F W H U P L Q D O G H Y L F